

Circolazione in curva

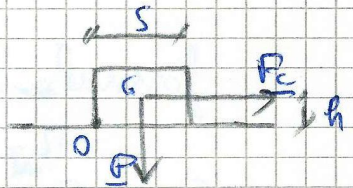
- Stabilizzatori in curva (verifica a bandamento):

$$a_c = \frac{v^2}{R} \Rightarrow F_c = m a_c = \frac{P}{g} \cdot \frac{v^2}{R}$$

Due casi:

- senza soproelevazione:

$$F_c \leq P f_a \Rightarrow \frac{P}{g} \frac{v^2}{R} \leq P f_a \Rightarrow v \leq \sqrt{g R f_a}$$

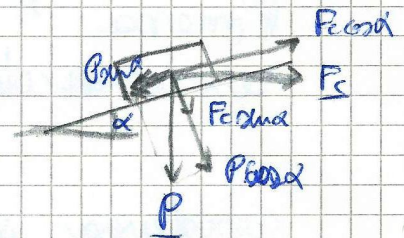


- con soproelevazione

$$F_c \leq P f_a$$

$$F_{cu} = F_c \cos \alpha \quad P_l = P \cos \alpha$$

$$F_{cl} = F_c \sin \alpha \quad P_{l1} = P \sin \alpha$$



$$\Rightarrow F_c \cos \alpha - P \sin \alpha \leq f_a (P \cos \alpha + F_c \sin \alpha)$$

$$\Rightarrow \frac{P v^2}{g R} \cos \alpha - P \sin \alpha \leq f_a \left(P \cos \alpha + \frac{P v^2}{g R} \sin \alpha \right) \quad / \cdot \frac{1}{\cos \alpha}$$

$$\Rightarrow \frac{v^2}{g R} - \tan \alpha \leq f_a \left(1 + \frac{v^2}{g R} \tan \alpha \right)$$

$$\Rightarrow \frac{v^2}{g R} (1 - f_a \tan \alpha) \leq f_a + \tan \alpha \quad f_a \tan \alpha \geq 0$$

$$\Rightarrow v \leq \sqrt{g R (f_a + \tan \alpha)}$$

- verifica a ribaltamento:

$$M_R = F_c \cdot h = m \frac{v^2}{R} h$$

$$M_S = P \frac{S}{2} = \frac{1}{2} m g S$$

$$\Rightarrow M_R \leq M_S \Rightarrow m \frac{v^2}{R} h \leq \frac{1}{2} m g S$$

$$\Rightarrow v^2 \leq \frac{1}{2} R h S \Rightarrow v \leq \sqrt{\frac{1}{2} R h S}$$

- allargamento curve:

$$e = \frac{K}{R}$$

K vale 30 o 45

- derivata di equazione $p S = A^2$ con A dato da:

$$\text{conbraccio } \varepsilon = \frac{d \ln v^2}{d \ln S} = \frac{d \left(\frac{v^2}{R^2} S \right)}{d \ln S} = \frac{v^2}{A} = \frac{50,4}{v} = \varepsilon_{max}$$

$$\Rightarrow A_{min} = \frac{v^2}{50,4} = \frac{v^2}{50,4} \quad \Rightarrow A_{max} = \frac{v^2}{-50,4}$$

- sopralandamento

$$A_{min} = \sqrt{\frac{R}{\Delta v}} B (q_1 + q_2) \quad B \text{ larghezza carreggiata e } \Delta v \text{ differenza lung}$$

- precisione ottica: $\frac{R}{3} \leq A \leq R$